

Example Sheet 3: Cartesian Tensors

- 1 (i) To what quantities do the following expressions in suffix notation (using summation convention) correspond? (Simplify where appropriate.)

$$\delta_{ii}; \quad \delta_{ij}a_j; \quad \delta_{ij}a_i a_j; \quad \delta_{ij}\delta_{ij}; \quad \epsilon_{iji}; \quad \epsilon_{ijk}\delta_{jk}; \quad b_i\epsilon_{ijk}a_k c_j; \quad \epsilon_{ijk}a_{3i}a_{1k}a_{2j}.$$

- (ii) For each of the following equations, either give the equivalent in vector or matrix notation, or explain why the equation is invalid.

$$\begin{aligned} x_i &= a_i b_k c_k + d_i; & x_i &= a_j b_i + c_k d_i e_k f_j; & u &= (\epsilon_{jkl} v_k w_l) x_j; \\ \epsilon_{ijk} x_j y_k \epsilon_{ilm} x_l y_m &= 1; & a_{ik} b_{kl} &= T_{ik} \delta_{kl}; & x_\alpha &= a_{\alpha i} b_{\beta i} y_\beta. \end{aligned}$$

- (iii) Write the following equations in suffix notation using summation convention. (A , B and C are matrices; Tr denotes the trace.)

$$\begin{aligned} (\mathbf{x} + \mu\mathbf{y}) \cdot (\mathbf{x} - \mu\mathbf{y}) &= 0; & \mathbf{x} &= |\mathbf{a}|^2 \mathbf{b} - |\mathbf{b}|^2 \mathbf{a}; & (2\mathbf{x} \times \mathbf{y}) \cdot (\mathbf{a} + \mathbf{b}) &= \lambda; \\ A\mathbf{x} &= \mathbf{b} - B^T \mathbf{y}; & (\mathbf{x} \cdot \mathbf{y}) \text{Tr } A &= 3|\mathbf{x} \cdot \mathbf{y}|; & |A\mathbf{x}|^2 &= \frac{1}{\mathbf{x} \cdot \mathbf{y}} \mathbf{y} \cdot (A^T B C \mathbf{x}). \end{aligned}$$

- 2 (i) Prove that

$$\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) = \mathbf{b} \cdot (\mathbf{c} \times \mathbf{a}) = \mathbf{c} \cdot (\mathbf{a} \times \mathbf{b}).$$

- (ii) Show that

$$\epsilon_{ijk}\epsilon_{klm} = \delta_{il}\delta_{jm} - \delta_{im}\delta_{jl}.$$

Hence find $\epsilon_{ijk}\epsilon_{ijk}$.

- 3 The moments of inertia along the principal axes \mathbf{e}_1 , \mathbf{e}_2 and \mathbf{e}_3 of a rigid body are 1, 2 and 3 respectively. (The off-diagonal components of the inertia tensor are zero in this frame.) An observer has a coordinate basis $\mathbf{e}'_1 = \frac{1}{2}(\mathbf{e}_1 + \sqrt{3}\mathbf{e}_3)$, $\mathbf{e}'_2 = \mathbf{e}_2$ and $\mathbf{e}'_3 = \frac{1}{2}(\mathbf{e}_3 - \sqrt{3}\mathbf{e}_1)$. Confirm that this is an orthonormal basis, and find the values of the components of the inertia tensor measured by the observer.

In a third frame with axes $\{\mathbf{e}''_1, \mathbf{e}''_2, \mathbf{e}''_3\}$, \mathbf{e}_1 has components $\frac{1}{\sqrt{2}}(1, 1, 0)$ relative to these axes and \mathbf{e}_2 has components $\frac{1}{\sqrt{3}}(1, -1, 1)$. Find the inertia tensor I_{ij} in this frame, and calculate $I_{ij}I_{ji}$. [There is a simple way to do this!]

- 4 Calculate the inertia tensor of a uniform right circular cylinder of mass M , radius a and height $\sqrt{3}a$, about its centre of gravity. Comment on your result.

5 A vector \mathbf{F} is related to vectors \mathbf{J} and \mathbf{H} by a linear relation of the form $F_i = A_{ijk}J_jH_k$. Starting from the transformation laws for the components of vectors, deduce the transformation law for the components of $A = (A_{ijk})$. Hence demonstrate that A is a third rank tensor.

6 (i) Explain why for a 3×3 matrix $A = (a_{ij})$,

$$\epsilon_{ijk} \det A = \epsilon_{lmn} a_{il} a_{jm} a_{kn}.$$

(ii) Show that ϵ_{ijk} is a third rank tensor. Explain why it is isotropic. [*In fact ϵ_{ijk} is a pseudo-tensor: ask your supervisor to explain.*]

(iii) Show that if A is a second rank tensor then $\det A$ is a scalar.

7 Show that any second rank tensor T may be expressed as the sum of a symmetric tensor with zero trace, an isotropic tensor and an anti-symmetric tensor.

The components of T are measured by one observer to be

$$\begin{pmatrix} 3 & -1 & 5 \\ 1 & 0 & 5 \\ 1 & -5 & 3 \end{pmatrix}.$$

Decompose T into three parts as above, and diagonalise the symmetric zero-trace part. Find the sum of the principal values of this part, and comment.

8 Let $A = (a_{ij})$ be an anti-symmetric second rank tensor. Show that for any vector \mathbf{x} , $A\mathbf{x}$ may be written as $\boldsymbol{\omega} \times \mathbf{x}$ for some suitable $\boldsymbol{\omega}$ which depends only on A .

Now show that the tensor $B = (b_{ij})$ defined by $b_{ij} = a_{ik}a_{kj}$ is symmetric, and find its principal values in terms of $\boldsymbol{\omega}$.

9 The electrical conductivity σ in a crystal is measured by an observer to have components

$$\begin{pmatrix} 1 & \sqrt{2} & 0 \\ \sqrt{2} & 3 & 1 \\ 0 & 1 & 1 \end{pmatrix}.$$

Show that there is one direction in which no current flows, and find that direction.

The rate of energy dissipation per unit volume is given by $E_i J_i$ where \mathbf{E} is the applied electric field and \mathbf{J} the resulting current density. For a fixed value of $|\mathbf{E}|^2$, find the minimum and maximum possible energy dissipation rates.

10 Show that the fourth rank tensor

$$c_{ijkl} = \alpha \delta_{ij} \delta_{kl} + \beta \delta_{ik} \delta_{jl} + \gamma \delta_{il} \delta_{jk}$$

is isotropic. For the rest of this question you may assume that it is in fact the most general isotropic tensor of rank four.

In an isotropic fluid moving with velocity $\mathbf{v}(\mathbf{x})$, the strain tensor e_{ij} is defined by

$$e_{ij} = \frac{1}{2} \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right)$$

and the corresponding stress tensor is σ_{ij} . The pressure in the fluid is given by $p = -\frac{1}{3}\sigma_{ii}$. Define the deviatoric stress tensor by $\sigma'_{ij} = \sigma_{ij} + p\delta_{ij}$: show that σ' has zero trace. In most fluids (known as *Newtonian fluids*) the deviatoric stress is linearly related to the strain; show that the relationship between σ and e must then take the form

$$\sigma_{ij} = 2\mu(e_{ij} - \frac{1}{3}\delta_{ij}e_{kk}) - p\delta_{ij}$$

for some scalar μ known as the coefficient of viscosity.

Given that $\mu > 0$, show further that the product $\sigma'_{ij}e_{ij}$ is non-negative (by considering its minimum value in an appropriate frame, or otherwise).

11 The rotationally symmetric crystal lattice of a simple metal has conductivity α parallel to its axis of symmetry and β in any perpendicular direction. Write down the conductivity tensor relative to these axes. A particular crystal is grown in such a way that it takes the form of a long thin wire, the direction of the wire making an angle θ with the symmetry axis of the lattice. By considering a current passing along the wire, show that the wire's resistance is $(L/A)(\alpha^{-1} \cos^2 \theta + \beta^{-1} \sin^2 \theta)$, where L is the length of the wire and A its cross-sectional area.

12 A second rank tensor is defined in terms of the position vector \mathbf{x} by $T_{ij} = \delta_{ij} + \epsilon_{ijk}x_k$. Calculate the following integrals, where in each case the integration is over the surface of the sphere of unit radius.

$$\iint x_i \, dS; \quad \iint T_{ij} \, dS; \quad \iint T_{ij}T_{jk} \, dS.$$

13 Use suffix notation to establish the following vector identities for any scalar field Φ and vector field \mathbf{F} :

$$\begin{aligned} \nabla \times (\nabla \Phi) &= \mathbf{0}; & \nabla \times (\Phi \mathbf{F}) &= \Phi \nabla \times \mathbf{F} + \nabla \Phi \times \mathbf{F}; \\ \nabla \cdot (\nabla \times \mathbf{F}) &= 0; & \mathbf{F} \times (\nabla \times \mathbf{F}) &= \nabla \left(\frac{1}{2} |\mathbf{F}|^2 \right) - (\mathbf{F} \cdot \nabla) \mathbf{F}. \end{aligned}$$

14 A conductor carries a steady current density $\mathbf{J} = \mu^{-1} \nabla \times \mathbf{B}$ in a magnetic field \mathbf{B} , where μ is the permeability. The mechanical force per unit volume acting on the conductor is $\mathbf{J} \times \mathbf{B}$. Show that this force can be written as $\partial S_{ij} / \partial x_j$ in terms of a tensor

$$S_{ij} = \mu^{-1} (B_i B_j - \frac{1}{2} B_k B_k \delta_{ij}).$$

[Note that $\nabla \cdot \mathbf{B} = 0$.]

Comments on or corrections to this problem sheet are very welcome and may be sent to me at reh10@damtp.cam.ac.uk.